



Visual Servoing: Real-Time Control of Robot Manipulators Based on Visual Sensory Feedback (World Scientific Series in Robotics and Automated Systems)

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Visual feedback control of mechanical systems, mostly robotic manipulators, is the subject of this book. It deals not only with image processing techniques and robot control schemes but also covers the latest investigation on design of visual servo mechanisms based on modern linear and nonlinear control theory, adaptive control scheme, fuzzy logic and neural networks. New concepts for utilizing visual sensory information to real-time manipulator control are derived and the performance is evaluated through simulations and/or experiments. The contributors to this book are from robotics specialists from all over the world. This book gives a practical perspective on visual servoing to the researcher, engineers and students working on this topic.

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