



Active Perception and Robot Vision (Nato ASI Subseries F:)

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Intelligent robotics has become the focus of extensive research activity. This effort has been motivated by the wide variety of applications that can benefit from the developments. These applications often involve mobile robots, multiple robots working and interacting in the same work area, and operations in hazardous environments like nuclear power plants. Applications in the consumer and service sectors are also attracting interest. These applications have highlighted the importance of performance, safety, reliability, and fault tolerance. This volume is a selection of papers from a NATO Advanced Study Institute held in July 1989 with a focus on active perception and robot vision. The papers deal with such issues as motion understanding, 3-D data analysis, error minimization, object and environment modeling, object detection and recognition, parallel and real-time vision, and data fusion. The paradigm underlying the papers is that robotic systems require repeated and hierarchical application of the perception-planning-action cycle. The primary focus of the papers is the perception part of the cycle. Issues related to complete implementations are also discussed.

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